**User Guide Specifications**

- Intended to provide information on **the design and implementation of your robot** which will be useful to anyone who wants to use your system

-Targeted towards somebody at the level of a first year CS student, and should let this person fully understand how to **take your code and your robot and get it demonstrate** what it is capable of

- between **4-6 pages**, illustrations and references will not count towards the limits.

-include diagram and tables; may contain appendices beyond the strict page limits but markers are not required to read these appendices (use them sparingly).

1. 3 marks for clarity of the installation instructions

* How to install your code, and any dependencies, onto a standard DiCE machine

2.  6 marks for comprehensiveness of the usage information

* An overview of your robot from the perspective of a potential user:
  + structural information such as how it can move, what sensors it is equipped with, and other functionality
  + usage information (how to turn it on, swap batteries, etc.). Include all the issues that a user might have to deal with when using your robot.
* An overview of your DiCE-resident software, (how to get it running, necessary calibration, and how to operate it)

3. 2 marks for the troubleshooting guide

- probably presented as a table

4. 4 marks for the quality of the presentation

The deadline for the user guide is **4pm on Friday 23rd March**